

# Real Time Image Segmentation

Miklos Homolya, Ravikishore Kommajosyula, Gaurav Kukreja

Technical University of Munich

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# Overview

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# Problem Definition

# OpenGL Interoperability

What is Interoperability?

- Mapping OpenGL Resources to CUDA, to enable CUDA to read/write
- Can be used to show output from CUDA kernel, straight from GPU saving time and bandwidth

# How to use OpenGL Interop?

- Set current threads OpenGL context to use for OpenGL interop with CUDA **device**.

```
cudaGLSetGLDevice(device);
```

- Create OpenGL Pixel Buffer, and register to use as CUDA buffer.

```
gl.glGenBuffers(1, &pixels);  
gl.glBindBuffer(GL_PIXEL_UNPACK_BUFFER, pixels);  
size_t size = w * h * 4 * sizeof(unsigned char);  
gl.glBufferData(GL_PIXEL_UNPACK_BUFFER, size, 0,  
               GL_DYNAMIC_DRAW);  
cudaGraphicsGLRegisterBuffer(&pixels_CUDA, pixels,  
                             cudaGraphicsMapFlagsWriteDiscard);
```

# How to use OpenGL Interop?

- Before starting kernel, map pixel buffer to a CUDA pointer.

```
cudaGraphicsMapResources(1, &pixels_CUDA, 0);  
cudaGraphicsResourceGetMappedPointer(&d_pixels, &size,  
    pixels_CUDA);
```

# References



John Smith (2012)

Title of the publication

*Journal Name* 12(3), 45 – 678.

# The End